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Quick Start with the Self-Driven Slot Car Development

Freescale Race Challenge 2009

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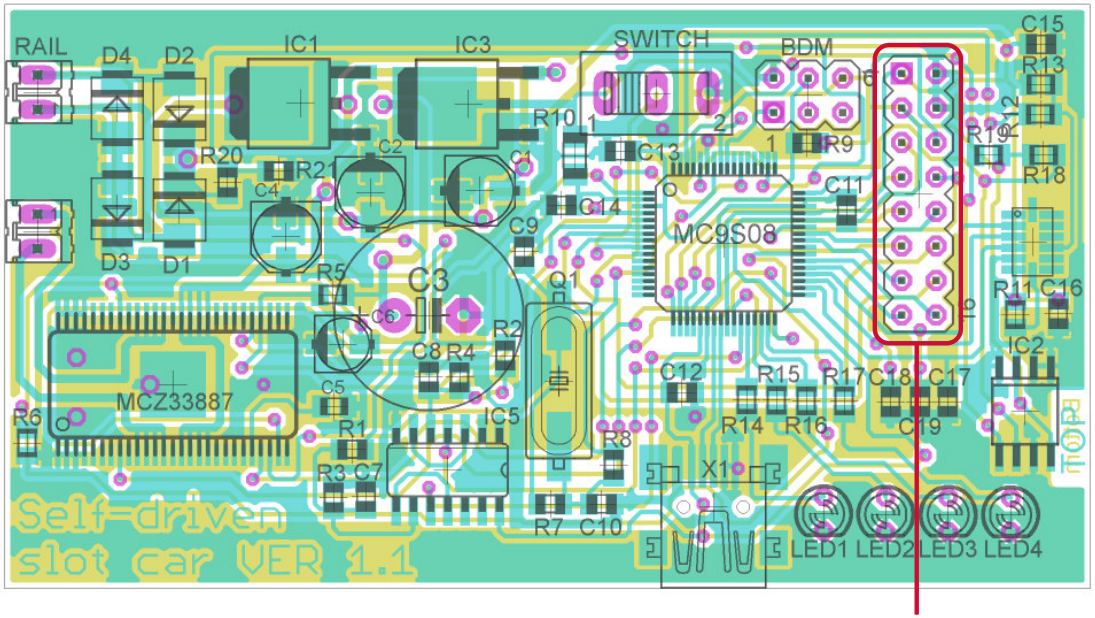
Freescale Race Challenge 2009: Quick Start

- Populate the PCB
- Build the electronics into the slot car
- Install development tools
- Open example application
- Program the flash memory
- Run the slot car on a test track
- Download the measured data from EEPROM to PC
  - Tip: Analyze the signal data in Matlab

- Develop your own self-driving algorithm

Populate PCB

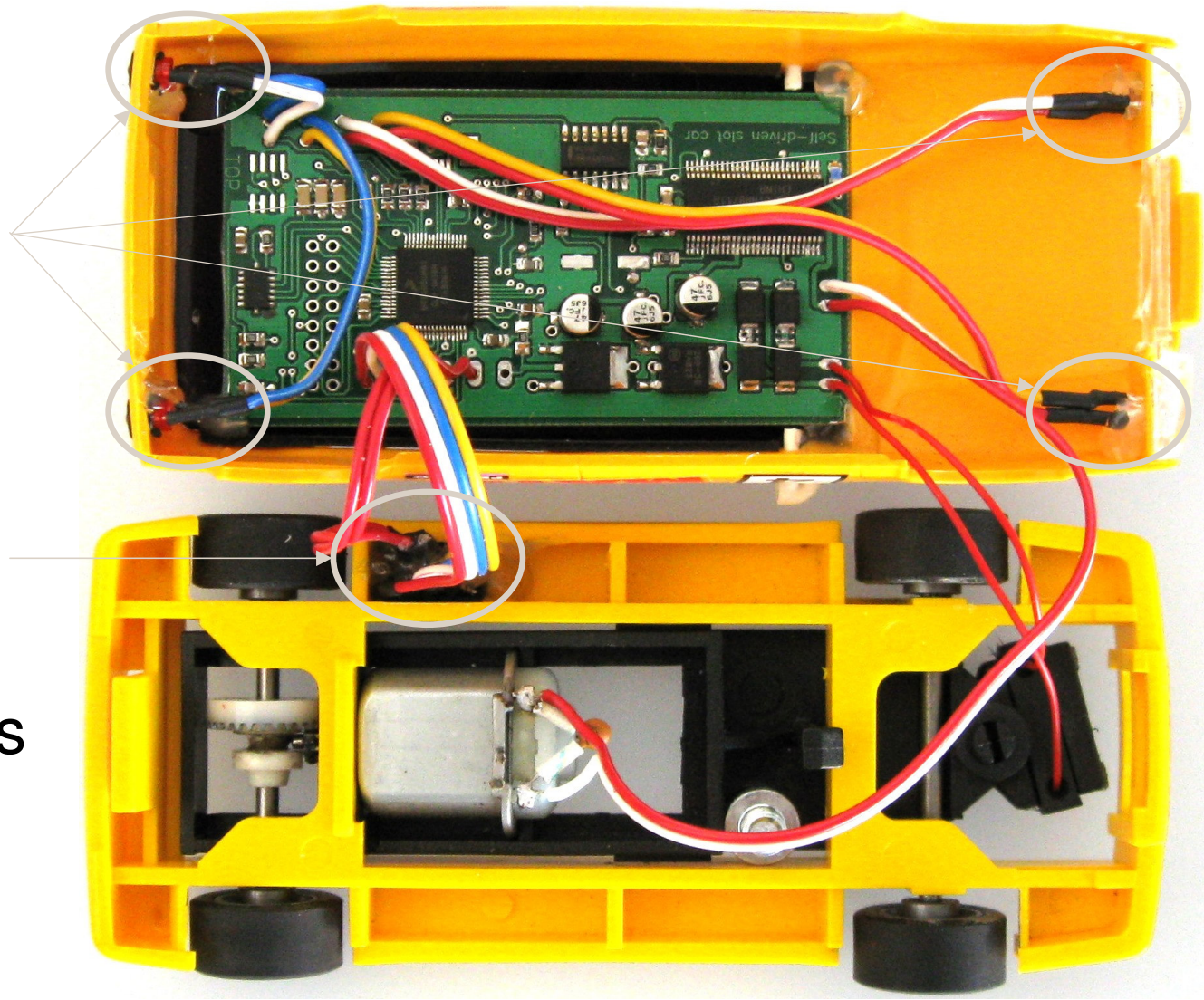
- Schematic,
  PCB layout and
  Bill Of Materials (BOM)
  available:
  - slot_car_equip\HW\schematic
  - slot_car_equip\HW\PCB
  - slot_car_equip\HW\BOM.txt



- Notes
  - You can design an expansion board and connect to the expansion connector available on the provided PCB.
  - You can exchange the S08JM 8-bit microcontroller with it's 32-bit brother MCF51JM in the same package and the same pinout.
  - You can redesign the slot car electronics by your own.
    - feel free to start from the provided schematic, layout and Eagle libs.

Build Electronics Into Slot Car

- Tips:
  - Mount LEDs into head and break lights for run-time diagnostics
  - Mount the BDM debugging connector and the switch to chassis for external access



Install Development Tools

- Install Freescale CodeWarrior
  - install\CW_MCU_V6_2_SE.exe
- Install Freescale FreeMASTER
  - install\fmaster13-8.exe

Open Example Application

- The example application project is available at
  - slot_car_equip\SW
- Run slot_car_equip\SW\project.mcp CodeWarrior project

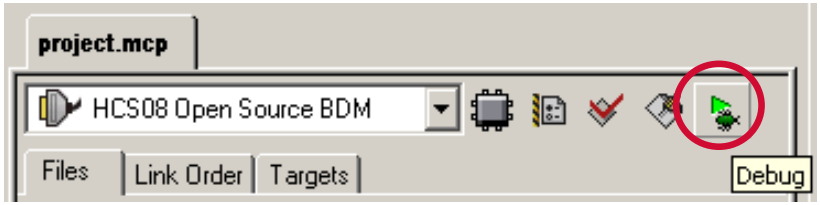
- The application code demonstrates how to:
  - initialize the S08JM32 microcontroller
  - use the motor H-bridge driver and drive the car
  - use the accelerometer and sample X, Y, and Z forces
  - sample motor current and DC-bus voltage
  - use the EEPROM and store/load measured data
  - use the LEDs and read the switch

Program Flash Memory

- Connect the OpenSourceBDM debugger to USB
- If prompted, install the OpenSourceBDM Windows driver
  - install\OpenSourceBDMDriver\OpenSourceBDM.inf

- Connect the debugger to the slot car BDM port

- Push Debug button in the CoderWarrior
  - confirm BDM connection
  - confirm flash re-writing

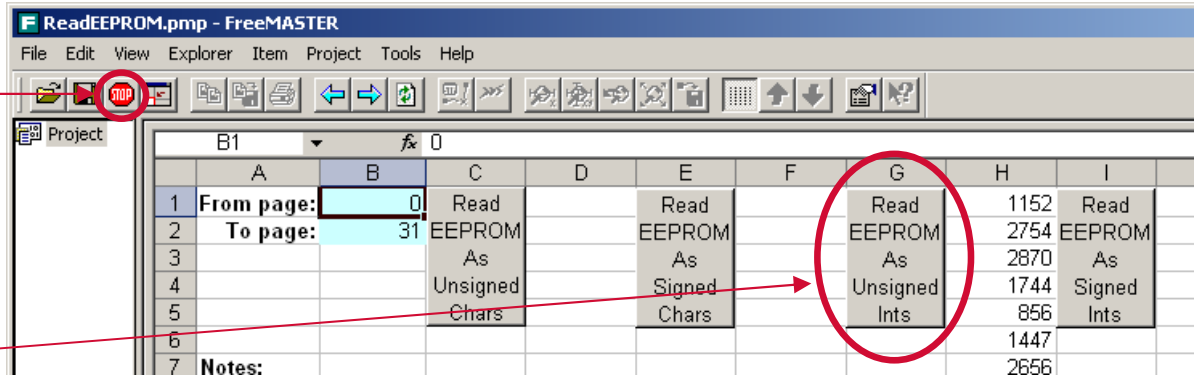


Run Slot Car on Test Track

Download Measured Data from EEPROM to PC

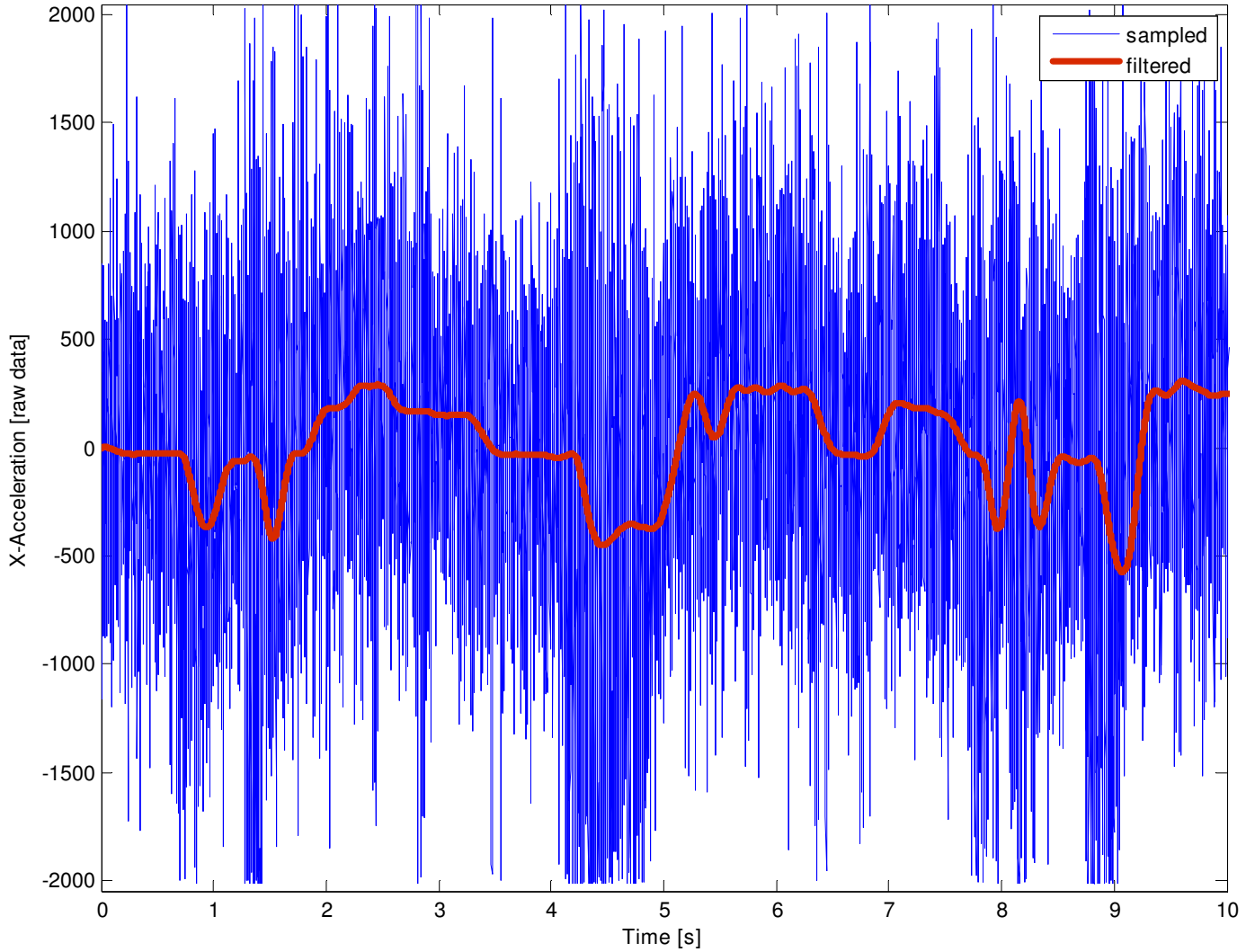
- Close CodeWarrior
- Connect the OpenSourceBDM debugger to the slot car

- Run ReadEEPROM.pmp FreeMASTER project
  - slot_car_equip\SW\ReadEEPROM.pmp
- Ensure the FreeMASTER communication with the car is established (STOP button is up)
- Push button Read ... in the integrated Excel application



EEPROM data read

Tip: Analyze The Signal Data in Matlab



Need more computational power?

- The provided microcontroller S08JM32
  - Belongs to the Controller Continuum family called Flexis
  - Has a Flexis "brother" MCF51JM with
    - ColdFire V1 32-bit core and more memory,
    - the same peripherals, the same package and the same pinout
- If your self-driving algorithm is getting to the edge of the S08JM power (only the most sophisticated algorithms could), exchange it with MCF51JM

Learn more about the Flexis family:
http://www.freescale.com/webapp/sps/site/overview.jsp?nodeId=016246233A3B62

Develop Your Own Self-Driving Algorithm

Good Luck!

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